## Comparison of the ASMO Car Model with Experimental Data and Simulations

Mike Gruetzmacher, Mentor Graphics



#### Content

- Introduction
- Physical Engineering Models
- The ASMO example
- Conclusion

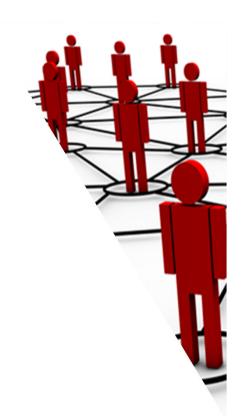




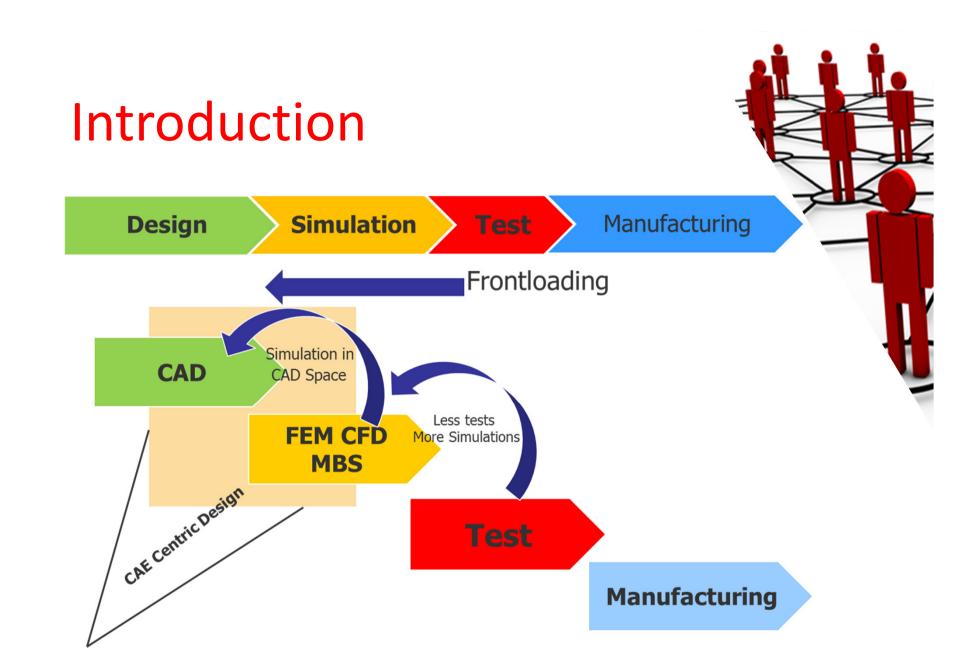
Velocity (m/s

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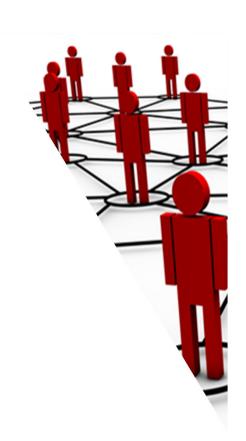




#### Introduction

- Early development phase
- Aerodynamics car analysis
  - Wind tunnel experiments
  - CFD analysis
- Increasing flexibility, cost reduction, design modifications
- Impact of components (e.g. radiator grill, rear wing, mirrors)





#### Introduction

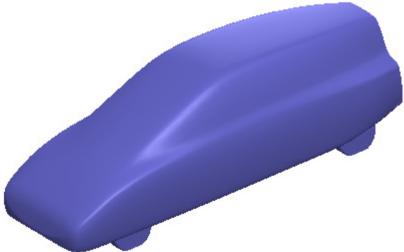
- Real car models: very complex geometry
- Simplified reference bodies for
  - Basic investigations
  - Code validations





#### Introduction

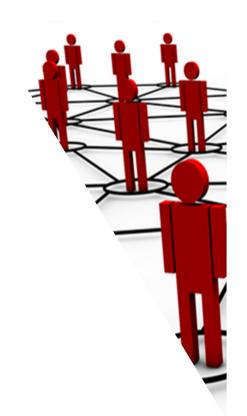
- ASMO example: "Aerodynamisches Studienmodell"
- Wind tunnel tests by Daimler Benz and Volvo





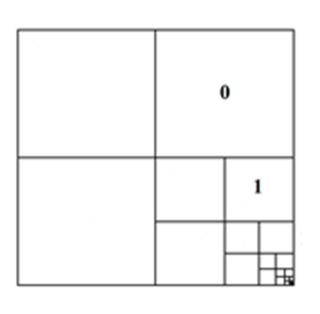
#### Content

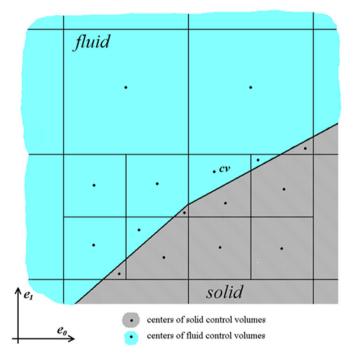
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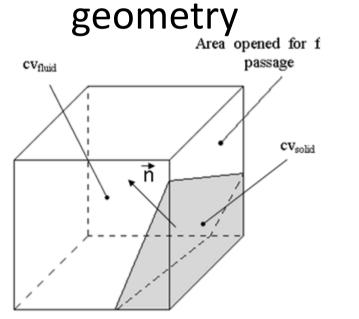


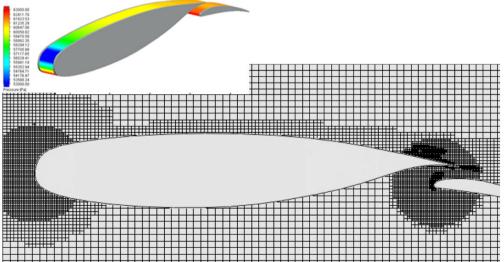
- Mesh: Rectangular Grid
- Refinements by cutting parallelepipeds





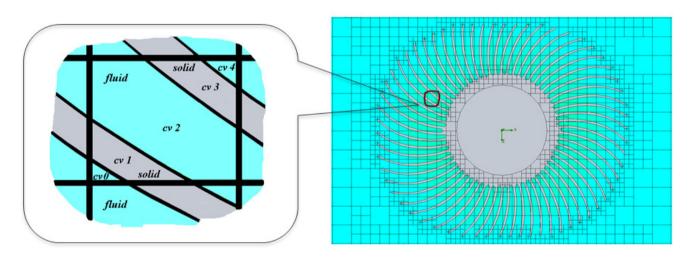
 Model body splits the cell into two or more sub-control volumes (polyhedrons) to represent the

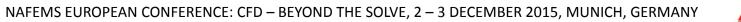






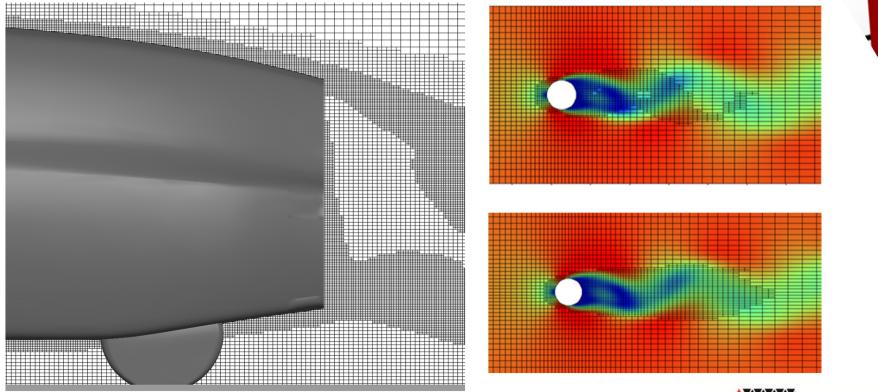
• Several sub-control volumes for very small features, f.i. thin layers







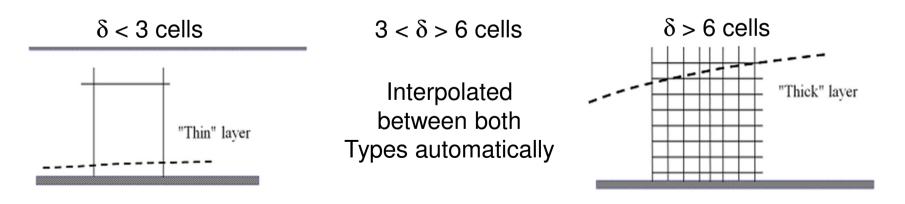
• Solution adaptive refinement for regions with high flow gradients

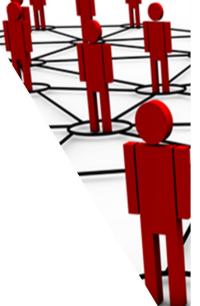




#### **Boundary Layer**

- FloEFD seperates the boundary layer treatment into:
  - "Thin" Boundary Layer
  - "Thick" Boundary Layer







## Physical Engineering Models

• One modified k-
$$\varepsilon$$
 turbulence model  
 $\frac{\partial \rho k}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i k) = \frac{\partial}{\partial x_i} \left( \left( \mu + \frac{\mu_t}{\sigma_k} \right) \frac{\partial k}{\partial x_i} \right) + S_k$   
 $\frac{\partial \rho \varepsilon}{\partial t} + \frac{\partial}{\partial x_i} (\rho u_i \varepsilon) = \frac{\partial}{\partial x_i} \left( \left( \mu + \frac{\mu_t}{\sigma_\varepsilon} \right) \frac{\partial \varepsilon}{\partial x_i} \right) + S_\varepsilon$ 

$$S_k = \tau_{ij}^R \frac{\partial u_i}{\partial x_j} - \rho \varepsilon + \mu_t P_B$$

$$S_{\varepsilon} = C_{\varepsilon_1} \frac{\varepsilon}{k} \left( f_1 \tau_{ij}^R \frac{\partial u_i}{\partial x_j} + \mu_t C_B P_B \right) - C_{\varepsilon_2} f_2 \frac{\rho \varepsilon^2}{k}$$

NAFEMS

#### Physical Engineering Models

- Algebraic solver is adapted to the mesh and the boundary layer treatment and includes the turbulence model in this approach
- high convergence stability and accuracy

### Physical Engineering Models

 Advanced Meshing Technology in FloEFD<sup>™</sup>

http://go.mentor.com/2gogl

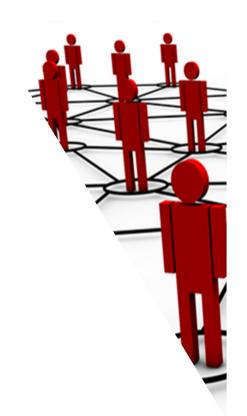
 Enhanced Turbulence Modelling in FloEFD<sup>™</sup>

http://go.mentor.com/2glzd



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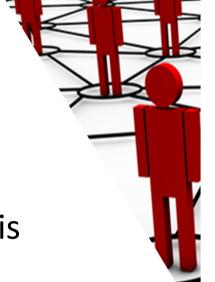




- Boundary Conditions
  - Velocity 50 m/s
  - Medium Air
  - Temperature 20 °C
  - Pressure 101,325 Pa
  - Reynolds Re=2,700,000 (vehicle length as reference)
- No movement applied to the floor surface (as in experiment)

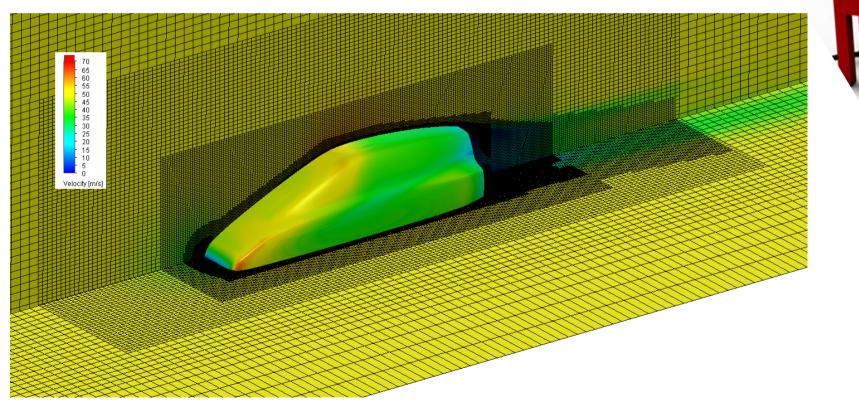


- Mesh:
  - Solution adaptive refinement used (two refinements are performed for this calculation)
- Number of cells:
  - Initial: 3.6 M
  - After the 2<sup>nd</sup> refinement: 13.5 M





• Calculated Mesh:





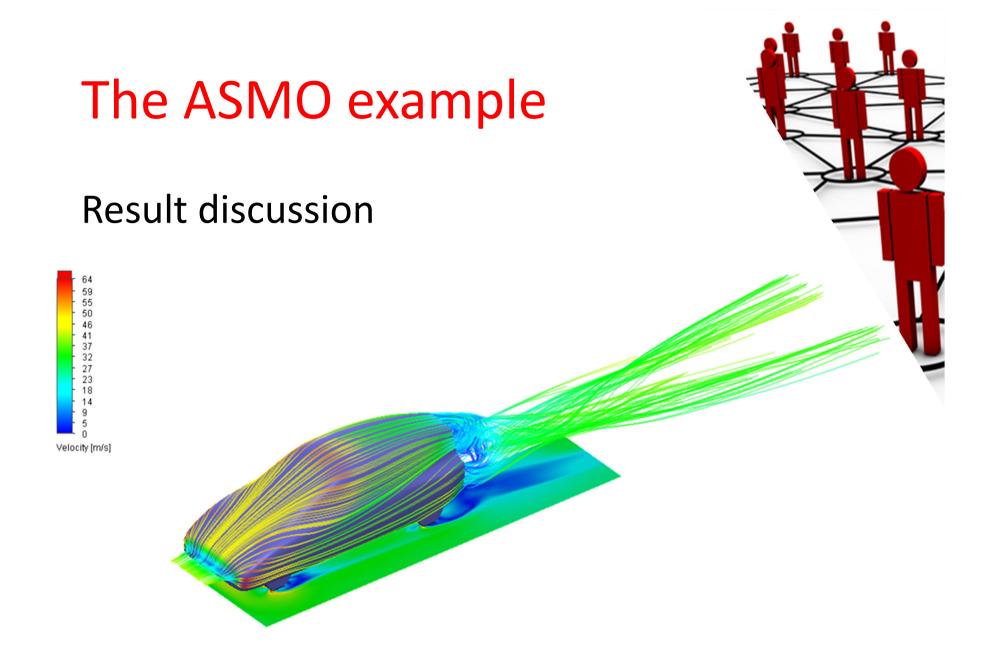
 Time Overhead Across the Simulation Workflow

Time Overhead Across the Simulation Workflow	in h	]
Setup Calculation project definition, pre-processing	1	
Solving time (including meshing and refinements)	18*	
Initial 1st automatic meshing time	0,03	(1,5 min)
Results processing	4	
Total	23	
User time, approximately	5	



\*Intel(R) Xeon(R) CPU E5-2630 v3 @ 2.40GHz (2 CPU)







• Drag Coefficient

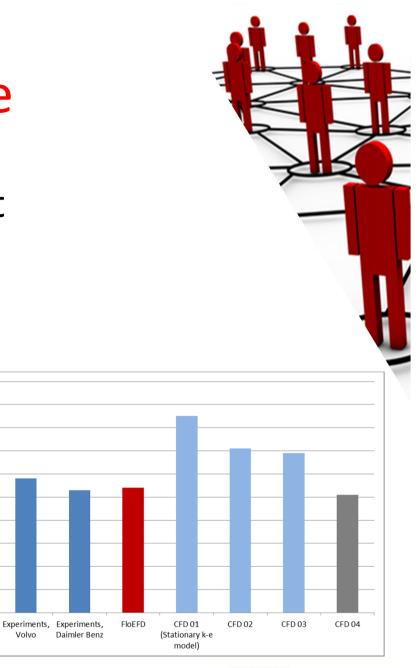
$$C_d = \frac{2F_d}{\rho u^2 A}$$

- $F_d$  = drag force in flow direction
- $\rho$  = fluid density
- u = fluid velocity
- A = projected surface



• Results: Drag Coefficient

Drag coefficient	
Experiments, Volvo	0,158
Experiments, Daimler Benz	0,153
FloEFD	0,154
CFD 01 (Stationary k-e model)	0,185
CFD 02	0,171
CFD 03	0,169
CFD 04	0,151





0,2 0,19 0,18 0,17 0,16 0,15 0,14 0,13 0,12 0,11 0,1

• Pressure Coefficient  $C_{P}$ 

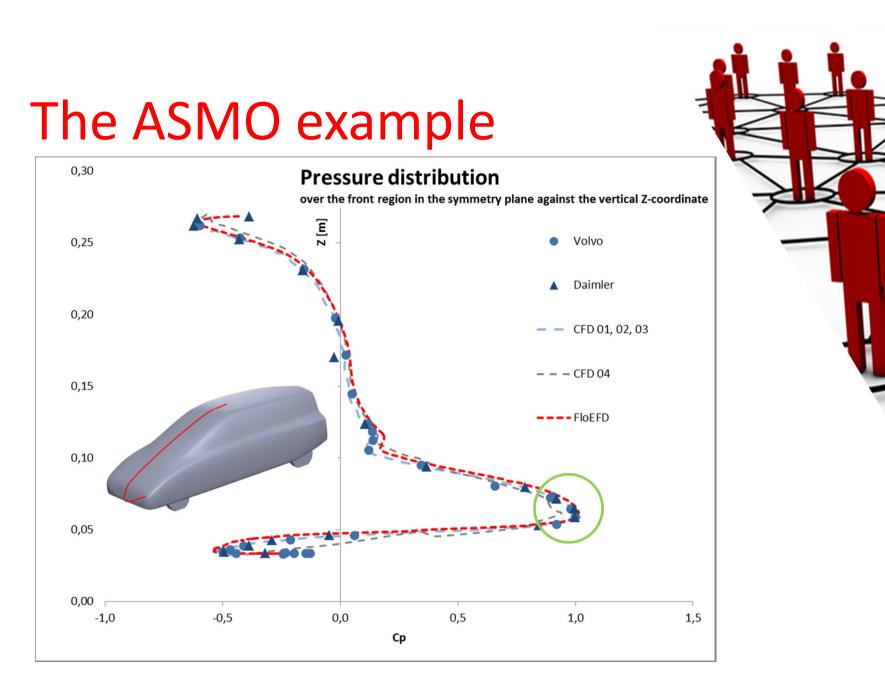
$$p = \frac{p - p_{\infty}}{\frac{1}{2}\rho_{\infty}v_{\infty}^2}$$

p = pressure at the corresponding point

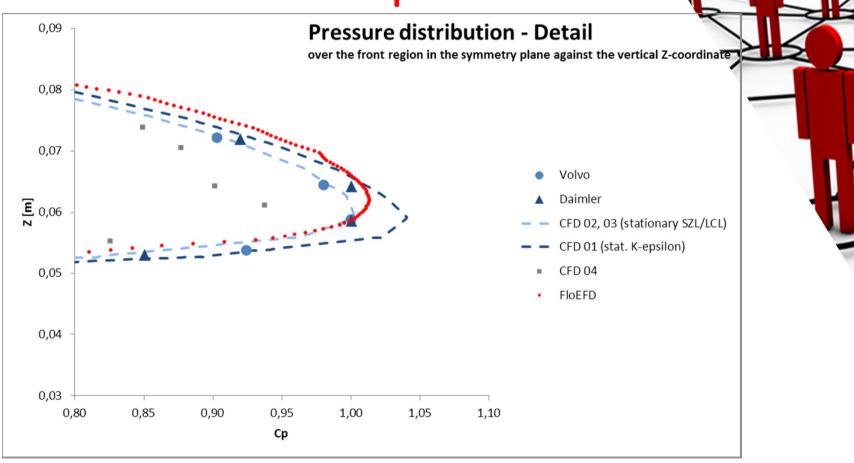
- $p_{\infty}$  = pressure in the freestream
- $\rho_{\infty}$  = fluid density in the freestream

 $v_{\infty}$  = freestream velocity

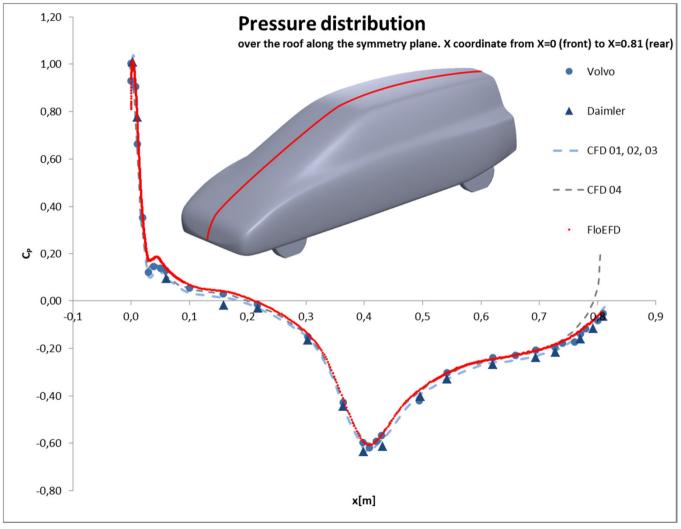










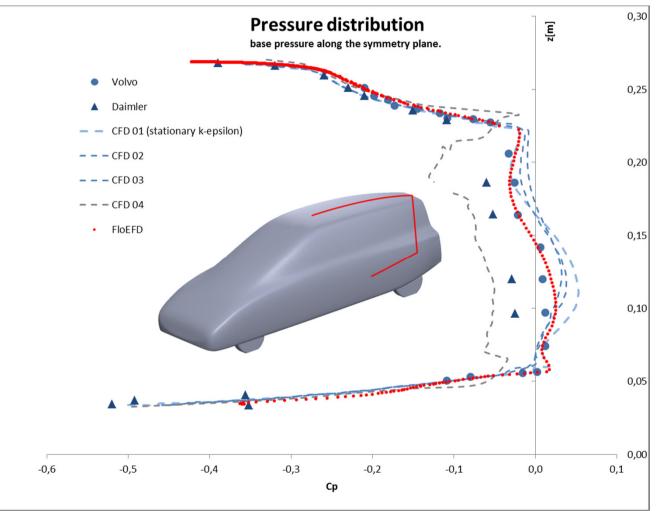




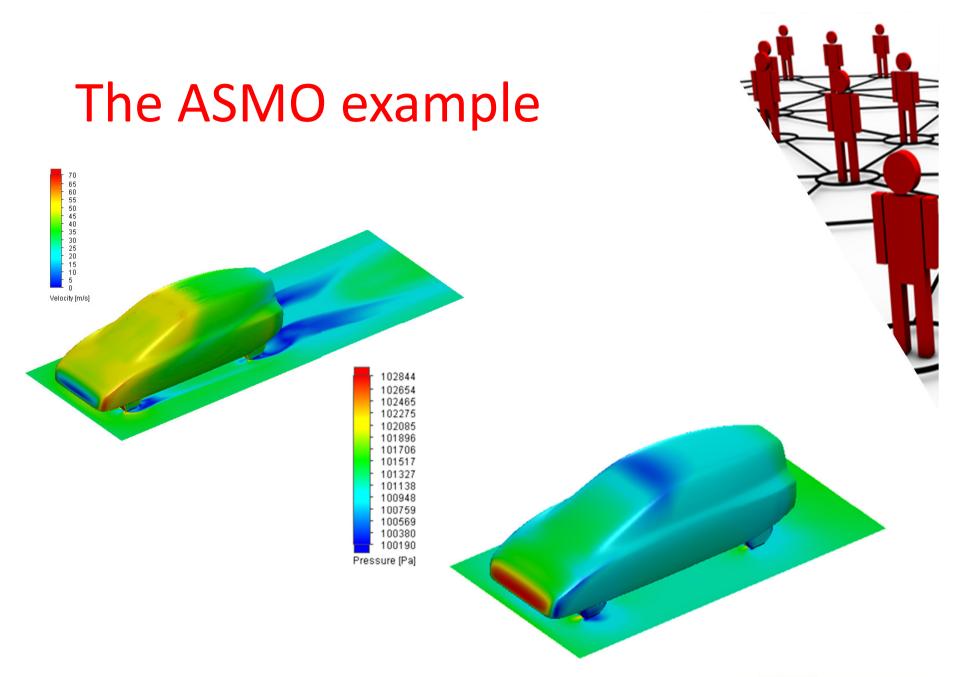


#### The ASMO example 1,20 **Pressure distribution** underbody along the symmetry plane. X coordinate from X=0 (front) to X=0.81 (rear) 1,00 Volvo A Daimler 0.80 CFD 01 (stationary k-epsilon) 0,60 - CFD 02, 03 -0,40 - - - CFD 04 **8** 0,20 FloEFD av. 0,00 0,1 0,2 0,3 0,4 0,5 0,6 0,7 0,9 -0,1 -0,20 -0,40 -0,60 -0,80 X[m]





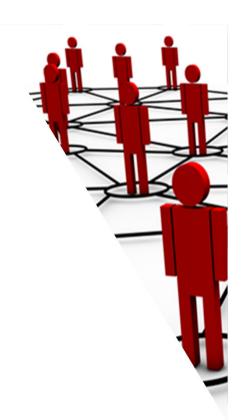






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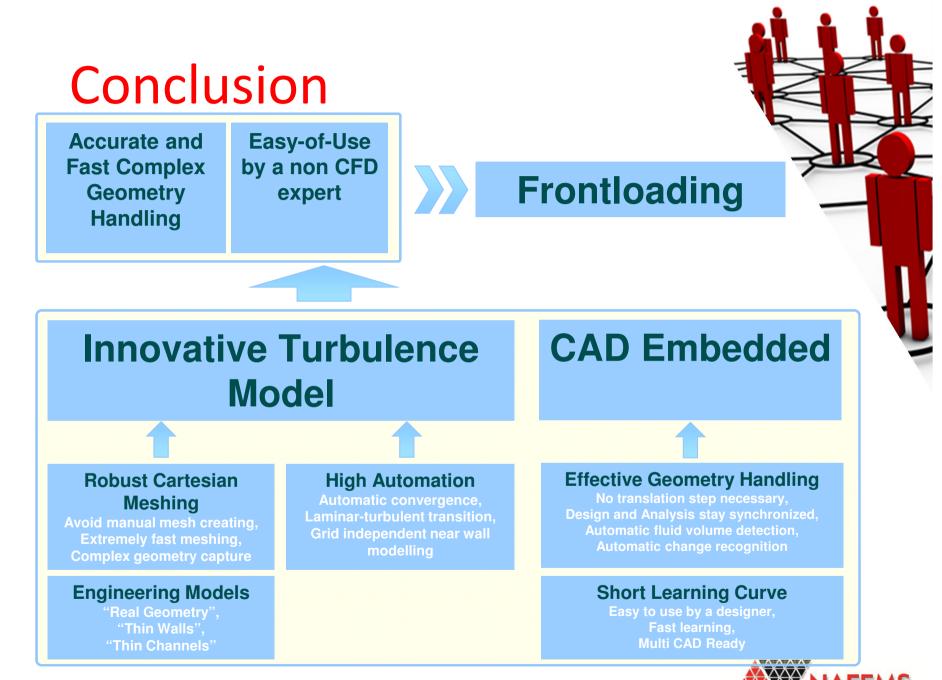


#### Conclusion

- Good agreement for the drag coefficient and the pressure coefficient curves
- Strong pressure coefficient variations due to turbulent wake influencing the diffuser area
- The CAD embedded CFD tool FloEFD shows reliable results









#### Conclusion

NAFEMS European Conference:

#### Computational Fluid Dynamics (CFD) – Beyond the Solve

The complete CFD activity chain across all industries from geometry to final conclusions – best practice methods and tools, automation, optimisation, verification and validation.

2 - 3 December, Munich, Germany

- CAD embedded simulation enables "Frontloading"
- Same level of accuracy compared to traditional, well established CFD tools and experimental results





# Thanks for your attention !

References

- [1] Whitepaper "Enhanced Turbulence Modeling In FloEFD", Mentor Graphics Corporation, 2011, http://go.mentor.com/2glzd
- [2] Perzon S., Davidson L.: "ON TRANSIENT MODELING OF THE FLOW AROUND VEHICLES USING THE REYNOLDS EQUATION", ACFD 2000 Beijing, 2000
- [3] http://www.xflowcfd.com/pdf/Project01-ASMO.pdf, "Aerodynamic analysis involving moving parts with XFlow", 2010
- [4] Marovic B., "CAD Embedded CFD vs. Traditional CFD Codes in a Blind JSAE Benchmark", NAFEMS World Congress 2015

