

## Sincenter Femap What's New in 2306



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#### SIEMENS

# What's new **Simcenter Femap 2306**

## **Teamcenter Integration**

Geometry

Preprocessing

Meshing

Performance Improvements

Analysis and Solver Support

Postprocessing

Miscellaneous and API



## Simcenter Femap 2306 Teamcenter Integration

Users can now specify multiple Teamcenter Server Environments via the PDM -> Teamcenter -> Sign In command

Server Definition items can be Added, Removed, Moved Up, and Moved Down in the Edit Teamcenter Server Environments dialog box

Once added, each server is then available in the drop-down

봧 Sign In To Teamcenter						
* User ID:						
* Password:						
Group:						
Role:						
* Server:						
Clear	Exton Pune Mumbai	]				

٧	Edit	Teamcenter Server Environments		×
		Server Name	Septer LIPI	
Ĩ	1	Exton	http://10.102.49.227:80/tc	
,	2	Pune	http://10.134.69.59:80/tc	
_	3	Mumbai	http://10.134.69.180:80/tc	-
			0%	
			OK Cance	1



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- Miscellaneous and API





Simcenter Femap 2306 Geometry – CAD Data Translators

CAD Data Translators migrated to Siemens standard PLMXML components, which offers:

- New Catia v6 translator! Supports .3dxml file
- New Inventor translator! Supports .ipt and .iam files
- New Rhino translator! Supports .3dm file
- Catia v5 translator now part of the base product!

Benefits

- Same User Interface for all translators
- Standard Siemens PLMXML Components are well maintained
- Easier for FEMAP development to keep CAD translators up to date

All Geometry (\*.x\_t;\*.sat;\*.stp;\*.igs;\*.pr ACIS (\*.sat) Parasolid (\*.x t) IGES (\*.igs) Stereolithography (\*.stl) AutoCAD DXF (\*.dxf) STEP (\*.stp) Catia v4.x (\*.mdl;\*.exp;\*.dlv) Catia v5 (\*.catp\*) Creo (\*.prt\*;\*.asm\*) Solid Edge (\*.par;\*.psm;\*.pwd;\*.asm) NX (\*.prt) SolidWorks (\*.sldprt;\*.sldasm) JT (\*.jt) Inventor (\*.ipt;iam) Rhino (\*.3dm) Catia V6 (\*.3dxml) All Geometry (\*.x t;\*.sat;\*.stp;\*.i ~ Cancel Open



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Simcenter Femap 2306 Preprocessing – Rotor Dynamics

## Simcenter Rotor Dynamics (SOL 414) is ....

A dedicated solution to Rotor Dynamics analysis

- An established, recognized rotor dynamics technology, SAMCEF (ROTORS)
- Best-in-class and complete rotor dynamics capabilities
- Uses Simcenter Nastran input format
- Flexible modelling & smart solutions for industry-sized problems
- Dedicated streamlined workflows and scenarios
- Ease-of-use & short learning curve
- Tokenable solution (Enterprise Nastran)





### Simcenter Femap 2306 Preprocessing – Rotor Dynamics

Rotor Dynamics analysis in Simcenter Nastran (SOL 414) is now supported

## New Element/Property Types

- Bearing
- Gear
- Fourier

## New Rotor Dynamics Entity Types

- XY Plot Definitions
- Bearing Speeds
- Rotational Speeds

New Load Types

- Unbalance Mass
- Unbalance Moment



Output Set: [2-Dynamics]Rotation Speed 8000 Rpm|Vibration modes | Flexible Mode 15, 1502.52 (Complex Phase: 0) Deformed(1.): Total Translation at Phase 0. Nodal Contour: Total Translation at Phase 0.

## SIEMENS

Bearing Element – writes CBEAR2 entry

 Defined by two nodes and a coordinate system

Bearing Property – writes PBEAR2 entry with TYPE field set to BEAR

- Constant stiffness, damping, and/or mass
- Option to have functionally-dependent stiffness, damping, and/or mass
  - Rotor Speed writes ROTF flag
  - Frequency writes FREQ flag
  - Time writes TIME flag
- Hysteretic Damping writes HYST and corresponding value
- Proportional Damping writes AVIS and corresponding value

Define Property - BEARING Element Type X											
ID 1	ID         1         Title         Material         E           Color         110         Layer         1         Elem/Property Type										
					D	amping Coe	fficie	nts			
Depen	dency Typ	e 0N	lo Deper	dency ~		OHystere	etic Da	amping (HYST	)	0.	
						Proport	ional I	Damping (AV)	IS)	0.	
Stiffr	ness (Kij)	Stiffnes	s (FKij)	Damping	(Cij)	Damping (	CKij)	Mass (Mij)	Mass (FMij)		
Stif	ffness Mat	rix Value	Entries	(11,12,	,21,22	2,,row,co	l) —		_		
1	1			2		3		4	5		6
1	0.		0.		0.		0.		0.	0	·
2	0.		0.		0.		0.		0.	0	
3	0.		0.		0.		0.		0.	0	
4	0.		0.		0.		0.		0.	0	
5	0.		0.		0.		0.		0.	0	
6	0.		0.		0.		0.		0.	0	
Defaults											
Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image: Second system     Image: Second system       Image: Second system     Image:											

Gear Element – writes CGEAR entry

 Defined as two nodes at center of two gears (separate rotors) and two coordinate systems

Gear Property – writes PGEAR entry

- Module of Gear pitch diameter of gear divided by number of teeth
- Gear A/Gear B
  - Number of Teeth must be > 0
  - Pitch Cone Angle in degrees
  - Helix Angle (deg)
- Pressure Angle (deg)
- Mesh Stiffness Coefficient (optional) if not specified, gears are considered rigid





## Simcenter Femap 2306

Preprocessing – Rotor Dynamics Element/Property Types

Fourier Element – writes FOU3 entry

- Connects a 3-D node with six DOF (Node A) to a 2-D node of a Fourier multi-harmonic (axisymmetric) element (Node B)
- Coupling Option writes appropriate value to OPT field on FOU3 entry
- Translational (OPT = 1) Nodes A and B must be coincident, translational DOFs are coupled
- Rigid Translational (OPT = 2) Node A must be a symmetry axis and Nodes A and B must have the same axial coordinate which creates a rigid connection between the translational DOF of the 3D node and the Fourier node
- All DOFs (OPT = 5) Similar to Rigid Translational, except all six DOFs are coupled, which allows the Fourier disk to deform (i.e., connection is not rigid)
- Can also be used in SOL 402

Define FOURIER Element - Enter Nodes or Select with Cursor X			
ID [1 Color 124	Layer 1 Property	∨ 🔥 Туре	
Nodes	Coupling Option 0Translational <->	OK Cancel	

## Fourier Property – none

#### SIEMENS

- The new Rotor Dynamics Entity Types can be access in two ways:
- Model -> Rotor Dynamics... menu
- In all cases, these commands display the dedicated Manager dialog box for the entity type
- Model Info tree Context-sensitive menus for each entity type offer ability to:
  - Create a New Entity
  - Display Manager for Entity Type
  - Copy Selected Entities
  - Edit Selected Entities
  - List Selected Entities
  - Delete Selected Entities
  - Renumber Selected Entities





XY Plot Definition – Defines an XY plot request for Nodal, Elemental, or Advanced output

• Writes both OUTMGT Case Control and corresponding OUTMGT Bulk Data entries

## XY Plot Definition Manager

- New Nodal Plot
- New Elemental Plot
- New Advanced Plot
- Edit Selected
- Show Selected
- Delete and Delete All
- Сору
- Renumber



## Simcenter Femap 2306

Preprocessing – Rotor Dynamics Entity Types

Nodal XY Plot – writes NODE or NODGRP to TYPE field of OUTMGT Bulk Data entries along with corresponding values for other fields based on selected Components, Coordinate System, and Quantity

- Displacement (DISP)
- Velocity (VELOC)
- Acceleration (ACCEL)
- Reaction Force/Moment (REAC)
- Elliptic Orbit Parameters (ORBITP)

Elemental XY Plot – writes ELEM or ELEMGRP to TYPE field of OUTMGT Bulk Data entries along with corresponding values for other fields based on selected Components and Quantity

- Stress (STRESS Top, Middle, and/or Bottom)
- Force (FORCE Top, Middle, and/or Bottom)

Nodal XY Plot Definition						
ID 1 Title						
Result Specifi	cation	Components				
Quantity	0Displacement V					
CSys	0Global Rectangular 🗸 🗸		2			
Selection						
Group	0None	~	<b>Q</b> }			
○ Node						
		<u>Q</u> K <u>C</u> ancel				





Advanced XY Plot – writes ELEM or ELEMGRP to TYPE field of OUTMGT Bulk Data entries along with corresponding values for other fields based on selected items on Stiffness, Mass, Damping, and/or Results tabs in lower portion of dialog box

Selected in Analysis Set Manager for available Rotor Dynamics Analysis Types

- SOL 414,103 Eigenvalue Analysis (Only when there is a transient response subcase)
- SOL 414,111 Harmonic Analysis
- SOL 414,129 Transient Analysis



Advanced XY Plot Definition	×
ID 1 Title	
Result	
Quantity 7Bearing Parameters V	
Selection	
Group     0None	~ 🔌 🕄
OElement	
Stiffness Mass Damping Results	
	All
□K21 □K22 □K23 □K24 □K25 □K26	None
□К31 □К32 □К33 □К34 □К35 □К36	
□K41 □K42 □K43 □K44 □K45 □K46	
□K51 □K52 □K53 □K54 □K55 □K56	
□К61 □К62 □К63 □К64 □К65 □К66	
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Bearing Speed – Connect Rotor Regions to Bearings when Bearing Properties are speed-dependent (Dependency Type = "1..Rotor Speed")

 Writes SPEBE2 Bulk Data entries which can be used with CBEAR2 which have the TYPE field on PBEAR2 set to BEAR or USER (not currently supported in Femap)

**Bearing Speed Manager** 

- New Bearing Speed
- Edit Selected
- Show Selected
- Delete and Delete All
- Сору
- Renumber





Bearing Speed – individual SPEBE2 entry written for each Bearing element that is selected in *Definition* section

Speed Option section defines possible user inputs

- Select Rotor Region(s) Select 1 or 2 rotors from the Rotor Specification section
  - Rotor Region 1 writes ID to RID1 field
  - *Rotor Region 2* writes ID to RID2 field
  - Rotating in the Same Direction option
  - When on, writes CORO to DIREC field
  - When off, writes COUN to DIREC field

Note: If only single rotor is selected, DIREC field is ignored

- Specify Table choose function in *Bearing Speed* section
- Writes ID of function to SPEED field Note: DIREC field to be ignored, as bearing speeds are explicitly defined by function

Bearing Speed		×	
ID 1	Title Bearing Speed Rotor 1 to Rotor 2		
Definition			
Bearing Elements	1 Elements	≥	
Speed Option			
Select Rotor F	Region(s) O Specify Table		
Rotor Specification			
Rotor Region 1	1Nastran ROTORG 1 V	<u>)</u>	
Rotor Region 2	4Nastran ROTORG 2 V	<u></u>	
Rotating in the Same Direction			
Bearing Speed			
Variation Table	0None 🗸	<mark>%</mark> ху	
		ł	



## Simcenter Femap 2306

Preprocessing – Rotor Dynamics Entity Types

Rotational Speed – Allows definition of rotation speeds in 3 different forms for use in Complex Modal analysis (SOL 414,110)

- Writes OMEGA, OMEGA1, or OMEGA2 entries with appropriate values
- Rotational Speeds are selected via Select Rotational Speed(s) dialog box available only for subcases with Analysis Type set to "2..Rotor Complex Modal"

## **Rotational Speed Manager**

- New Rotational Speed
- Edit Selected
- Show Selected
- Delete and Delete All
- Сору
- Renumber







Rotational Speed – entry written to input file depends on option selected for *Variation Type* in *Definition* section

- Individual Rotation Speeds (OMEGA) writes OMEGA entry
- Values in Y column of *Function* selected in *Rotational* Speed Table section are written to Wi fields
- *Linear Sweep (OMEGA1)* writes OMEGA1 entry
- First Rotational Speed value written to W1 field
- Rotational Speed Increment value written to DW field
- *Number of Increments* value written to NDW field
- *Logarithmic Sweep (OMEGA2)* writes OMEGA2 entry
  - *First Rotational Speed* value written to W1 field
  - Last Rotational Speed—value written to W2 field
  - *Number of Increments* value written to NDW field

Rotational Speed			×
ID 1	Title OMEGA	1 from 5000 RPM to	100000 RPM
Definition			
Variation Type	1Linear Swee	p (OMEGA1)	~
Rotational Speed Ta	able		
Function	0None		<ul> <li>✓ <sup>f</sup>xy</li> </ul>
Increment Specifica	tions		
First Rotational Spe	ed	5000	
Rotational Speed Ir	orement	5000	
Number of Increme	nts	19	
		<u>O</u> K	<u>C</u> ancel



The Model -> Load -> Nodal command can be used to create two new load types specific to Rotor Dynamics:

- Unbalance Mass
- Unbalance Moment

Both types:

- Require a *Rotor Region* be selected
- Allow a function to be specified as a Speed Table (option)
- Can only be used for SOL 414,111 (Subcase only) or SOL 414,129 by selecting them via *Boundary Conditions*
- Are written to UNBA Bulk Data entries referenced by ULOAD Case Control entry in specified case





### **Unbalance Mass**

- Rotor Region writes ID to RID field
- Speed Table writes ID of function to SPEED field
- Mass writes value to MASS field
- Eccentricity writes value to ECC field
- Phase writes value to PHASEF field
- Time/Freq Dependence writes ID of vs Time function to VBAL field

Note: If values for MASS, ECC, and VBAL are all specified, MASS and ECC are ignored by solver





## **Unbalance Moment**

- Rotor Region writes ID to RID field
- Speed Table writes ID of function to SPEED field
- Moment writes value to MOMENT field
- Angle writes value to THETA field
- Phase value written to PHASEM field
- Time/Freq Dependence writes ID of vs Time function to MBAL field

Note: If values for MOMENT, THETA, and VBAL are all specified, MOMENT and THETA are ignored by solver





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## Simcenter Femap 2306 Meshing – Mesh -> Region Enhancement

The Mesh -> Region command has been in Femap for a very long time, but was enhanced to a large extent for 2306

In previous versions, the node numbering needed to be in a very specific order for the command to create appropriate elements between the two sets of selected nodes ("Region 1" and "Region 2")

In 2306, the only requirement that remains is that the same number of nodes be selected for "Region 1" and "Region 2".



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## Simcenter Femap 2306 Meshing – Mesh -> Region Enhancement

Starting Model – No Geometry



#### Regions Selected Vertical Middle Area



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## Simcenter Femap 2306 Meshing – Mesh -> Region Enhancement

Horizontal Gaps in Mesh Skipped



## Mesh Fully Connected by using Mesh -> Region Again





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Simcenter Femap 2306 Performance Improvements – Graphics

Data Structures were defined and modified to allow Unified Graphics Architecture (UGA), first introduced in 2301, to be able to handle Nodes and Elements in an upcoming version

Improved performance of dynamic rotation in larger models which essentially had a property defined for each element in the model

 One example was a model that had 2 Million 10-noded tetrahedral elements and 2 million properties which went from rotating at 5 frames/second to between 30-40 frames/second on the same hardware (6X-8X improvement)





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Five new analysis types for Rotor Dynamics have been added for Simcenter Nastran

- "34...Rotor Dynamics Maneuvers" (SOL 414,101) Linear static analysis with rotational forces
- "35..Rotor Dynamics Eigenvalue Analysis" (SOL 414,103) Compute modes of the rotating system at rest
- "36..Rotor Dynamics Complex Modal Analysis" (SOL 414,110) Find critical speeds and stability of rotating system
- "37..Rotor Dynamics Harmonic Response" (SOL 414,111) Model rotating system under synchronous/asynchronous frequencydependent excitation
- "38..Rotor Dynamics Transient Response" (SOL 414,129) Direct solution to model rotating system under time-dependent excitation

Analysis Set	:	×
Title		]
Analysis Program	36Simcenter Nastran V	]
Analysis Type	1Static 🗸	
Solve Using	1Static 2Normal Modes/Eigenvalue 3Transient Dynamic/Time History	L
<ul> <li>Integrated Solver</li> </ul>	4Frequency/Harmonic Response 5Response Spectrum 6Random Response	
C Linked Solver	7Buckling 8Design / Topology Optimization	
	10Nonlinear Static 12Nonlinear Transient Response 20Steady-State Heat Transfer	
Next	21. Advanced Nonlinear Static 23. Advanced Nonlinear Transient	L
	25Static Aeroelasticity 26Aerodynamic Flutter 27Multi-Step Structural 28Multi-Step Nonlinear Kinematic	
	31Aeroelastic Frequency Response 32Aeroelastic Transient Response 33Aeroelastic Random Response	
	34Rotor Dynamics Maneuvers 35Rotor Dynamics Eigenvalues 36Rotor Dynamics Complex Modal Analysis 37Rotor Dynamics Harmonic Response 38Rotor Dynamics Transient Response	



Much like other types of analysis, each type of Rotor Dynamics analysis requires specific inputs

New and updated dialog boxes available for all SOL 414 analysis types include:

- NASTRAN Rotor Dynamics Options New!
- Rotor Modeling Assembly Selection New!
- Boundary Conditions Unique for Rotor Dynamics

Other new dialog boxes that may be used for specific type of SOL 414 analysis include:

- Select XY Plot Definition(s)
- Select Rotational Speed(s)

NASTRAN Rotor Dynamics Options X				
Activate Rotor Dynamics Solution Options				
Rotor Speed Variation Type	1Linear by Steps 🛛 🗸			
Start Value (RSTART)	0.			
Step Size (RSTEP)	0.			
Number of Steps (NUMSTEP)	0			
Reference System (REFSYS)	1Rotating ~			
Rotor Speed Input Unit (RUNIT)	0RPM - Rev/Min V			
Whirl Direction Threshhold (ORBEPS)	1.E-6			
.f06 Output (ROTPRT)	0None v			
Freq Resp Analysis Type (SYNC)	0Synchronous ~			
Parameters				
FHPOST	52D and 3D Results $\sim$			
FHPNST	12			
	1.E-4			
	0.9			
Pre <u>v</u> Ne <u>x</u> t	<u>O</u> K Canc <u>e</u> l			



Simcenter Femap 2306 Analysis and Solver Support – Simcenter Nastran – Rotor Dynamics The NASTRAN Rotor Dynamics Options dialog box is used to specify the Rotor Dynamics Solution Options as well as Parameters used for certain types of analysis

Activate Rotor Dynamics Solution Options – when on, entries in specified in ROTORD section are written to input file

- Rotor Speed Variation Type Used to limit available inputs for reference rotor speed
- "0..Constant" reference rotor speed remains constant, thus only Start Value (RSTART) can be entered
- "1..Linear by Steps" (Default) Enter values for Start Value (RSTART), Step Size (RSTEP), and Number of Steps (NUMSTEP) to define varying rotor reference speed
- "2..Function of a Sweeping Parameter" Rotor speed defined in another manner (OMEGAi, FREQi, or TSTEPi)

NASTRAN Rotor Dynamics Options X					
	Activate Rotor Dynamics Solution Options				
ſ	ROTORD				
	Rotor Speed Variation Type	1Linear by Steps $\sim$			
	Start Value (RSTART)	0.			
	Step Size (RSTEP)	0.			
	Number of Steps (NUMSTEP)	0			
	Reference System (REFSYS)	1Rotating ~			
	Rotor Speed Input Unit (RUNIT)	0RPM - Rev/Min 🗸 🗸			
	Whirl Direction Threshhold (ORBEPS)	1.E-6			
	.f06 Output (ROTPRT)	0None v			
	Freq Resp Analysis Type (SYNC)	0Synchronous ~			
	Parameters				
	FHPOST	52D and 3D Results $\sim$			
	FHPNST	12			
	✓ DFREQ	1.E-4			
		0.9			
[	Pre <u>v</u> Ne <u>x</u> t	<u>O</u> K Cancel			



- Start Value (RSTART) value written to RSTART field
- Step Size (RSTEP) value written to RSTEP field
- Number of Steps (NUMSTEP) value written to NUMSTEP field
- *Reference System (REFSYS)* Frame of Reference
  - "0..Fixed" specifies "fixed" frame of reference and writes 'FIX' to REFSYS field
  - "1..Rotating" (Default) specifies "rotating" frame of reference and writes 'ROT' to REFSYS field

NASTRAN Rotor Dynamics Options				
Activate Rotor Dynamics Solution Options				
Rotor Speed Variation Type	1Linear by Steps $\sim$			
Start Value (RSTART)	0.			
Step Size (RSTEP)	0.			
Number of Steps (NUMSTEP)	0			
Reference System (REFSYS)	1Rotating ~			
Rotor Speed Input Unit (RUNIT)	0RPM - Rev/Min 🗸 🗸			
Whirl Direction Threshhold (ORBEPS)	1.E-6			
.f06 Output (ROTPRT)	0None ~			
Freq Resp Analysis Type (SYNC)	0Synchronous ~			
Parameters				
FHPOST	52D and 3D Results 🗸 🗸			
FHPNST	12			
DFREQ	1.E-4			
	0.9			
Pre <u>v</u> Ne <u>x</u> t	<u>O</u> K Canc <u>el</u>			



- Rotor Speed Input Unit (RUNIT) selects units for rotor speed input, written to RUNIT field
  - "0..RPM Revs/Min" (Default) writes 'RPM' characters
  - "1..CPS Cycles/Sec" writes 'CPS' characters
  - "2..HZ Hertz" writes 'HZ' characters
  - "3..RAD Radians/Sec" writes 'RAD' characters
- Whirl Direction Threshold (ORBEPS) threshold value for detection of whirl direction written to ORBEPS field

NASTRAN Rotor Dynamics Options	×
Activate Rotor Dynamics Solution Op	otions
Rotor Speed Variation Type	1Linear by Steps V
Start Value (RSTART)	0.
Step Size (RSTEP)	0.
Number of Steps (NUMSTEP)	0
Reference System (REFSYS)	1Rotating ~
Rotor Speed Input Unit (RUNIT)	0RPM - Rev/Min 🗸 🗸
Whirl Direction Threshhold (ORBEPS)	1.E-6
.f06 Output (ROTPRT)	0None ~
Freq Resp Analysis Type (SYNC)	0Synchronous ~
Parameters	
FHPOST	52D and 3D Results 🗸 🗸
FHPNST	12
	1.E-4
	0.9
Pre <u>v</u> Ne <u>x</u> t	<u>O</u> K Canc <u>el</u>



- .f06 Output (ROTPRT) controls output written to .f06 file by specifying value for ROTPRT field
- "0..None" (Default) writes 0, prints nothing
- "1..Generalized Matrices" writes 1, prints:
  - Generalized matrices
  - Final nonlinear bearing values at each frequency/time
- "2..Eigenvalue Summary/Eigenvectors" writes 2, prints:
  - Eigenvalue summary and eigenvectors at each RPM
  - Intermediate nonlinear bearing values at each iteration
- "3..Both" writes 3, prints combination of 1 and 2
- Freq Resp Analysis Type (SYNC) option for frequency Response analysis
  - 0..Asynchronous writes value of 0 to SYNC field
  - 1..Synchronous (Default) writes value of 1 to SYNC field

NASTRAN Rotor Dynamics Options	×
Activate Rotor Dynamics Solution Op	otions
Rotor Speed Variation Type	1Linear by Steps 🗸
Start Value (RSTART)	0.
Step Size (RSTEP)	0.
Number of Steps (NUMSTEP)	0
Reference System (REFSYS)	1Rotating ~
Rotor Speed Input Unit (RUNIT)	0RPM - Rev/Min V
Whirl Direction Threshhold (ORBEPS)	1.E-6
.f06 Output (ROTPRT)	0None ~
Freq Resp Analysis Type (SYNC)	0Synchronous ~
Parameters	
FHPOST	52D and 3D Results $\sim$
FHPNST	12
DFREQ	1.E-4
	0.9
Pre <u>v</u> Ne <u>x</u> t	<u>O</u> K Canc <u>el</u>



Parameters section

- FHPOST Specifies the results output option when the axisymmetric Fourier elements are requested with the FHAR Case Control Command by writing PARAM, FHPOST
- "1..2D and 3D Results + 3D Recombination" writes value of 1, which Requests 3D harmonic results for the axisymmetric Fourier elements at incremental angle locations around the complete 360 degree circumference by using FHPNST parameter to define the angle increments per 90 degrees. In addition, writes out all output requested by option "5..2D and 3D Results"
- "4..2D Results" writes value of 4, which requests 2D results on the modeled axisymmetric geometry
- "5..2D and 3D Results" (Default) writes value of 5, which requests 2D results on the modeled axisymmetric geometry and 3D results on the modeled solid element geometry



Parameters section

- FHPNST Specifies the number of angle increments in a 90-degree quadrant in which the software computes the 3D harmonic results for axisymmetric Fourier elements, which allows users to view the non-axisymmetric results on a full revolute mode
  - Writes PARAM, FHPNST with entered value
  - Default value is 12, which is minimum value for FHPNST
- Used in conjunction with "1..2D and 3D Results + 3D Recombination" option specified for FHPOST
- DFREQ Specifies threshold for the elimination of duplicate frequencies (or rotational speeds) on all FREQi (or OMEGAi) entries, by writing PARAM, DFREQ with entered value
- RDMTRAK Specifies threshold value for mode tracking in SOL 414,110, writes PARAM,RDMTRAK with entered value

NASTRAN Rotor Dynamics Options	×
Activate Rotor Dynamics Solution Op	otions
Rotor Speed Variation Type	1Linear by Steps v
Start Value (RSTART)	0.
Step Size (RSTEP)	0.
Number of Steps (NUMSTEP)	0
Reference System (REFSYS)	1Rotating ~
Rotor Speed Input Unit (RUNIT)	0RPM - Rev/Min V
Whirl Direction Threshhold (ORBEPS)	1.E-6
.f06 Output (ROTPRT)	0None v
Freq Resp Analysis Type (SYNC)	0Synchronous ~
Parameters	
FHPOST	52D and 3D Results 🗸 🗸
FHPNST	12
DFREQ	1.E-4
	0.9
Pre <u>v</u> Ne <u>x</u> t	<u>O</u> K Canc <u>e</u> l



The Rotor Modeling Assembly Selection dialog box is used to select which Rotor Region(s) in model will be considered during the analysis, with minimum number of Rotors being 1 and maximum number being 10

Each *Rotor* #, *Function*, and *Value* combination is used to write lines 3 though 12, as needed, on the ROTORD entry

## Rotor Region Selection section

 Rotor 1 through Rotor 10 – writes ID of selected Rotor Region to appropriate RIDi field

Note: Rotation Axis (Z Axis), Freq for Overall Damping (W3), Freq for Material Damping (W4), and Rotational Force Applied on Rotor Region are written to RCORDi, W3\_i, W4\_i, and RFORCEi fields, as needed

Rotor Modeling	Assembly Selection					$\times$
Rotor Region Se	election		Rotor Speed Mult	iplier		
			Function		Value	
Rotor 1 *	1Nastran ROTORG 1	~	0None	$\sim$	1.	
Rotor 2	4Nastran ROTORG 2	~	0None	~	1.	
Rotor 3	0None	~	0None	$\sim$	1.	
Rotor 4	0None	~	0None	$\sim$	1.	
Rotor 5	0None	~	0None	$\sim$	1.	
Rotor 6	0None	~	0None	$\sim$	1.	
Rotor 7	0None	~	0None	$\sim$	1.	
Rotor 8	0None	~	0None	$\sim$	1.	
Rotor 9	0None	~	0None	$\sim$	1.	
Rotor 10	0None	~	0None	$\sim$	1.	
Prev	Ne <u>x</u> t	<mark>́х</mark> у	<u>О</u> К		Canc <u>e</u> l	



Rotor Speed Multiplier section

- *Function* when specified, writes ID of selected function to appropriate SPEEDi field as an integer
- If Step Size (RSTEP) value in NASTRAN Rotor Dynamics Options dialog box is:
  - Non-Zero defines values of the multiplier as a function of reference rotor speed
  - 0 defines values of the rotor speed as a function of the sweeping parameter with sweeping parameter specified as OMEGAi for SOL 414,110, FREQi for SOL 414,111, or TSTEPi for SOL 414,129
- Value if function is not specified, writes value to appropriate SPEEDi field as real number, which is a multiplier of all reference rotor speeds

Rotor Modeling	Assembly Selection		×
Rotor Region Se	election	Rotor Speed Multiplier	
		Function	Value
Rotor 1*	1Nastran ROTORG 1 🛛 🗸	0None 🗸	1.
Rotor 2	4Nastran ROTORG 2 🛛 🗸	0None ~	1.
Rotor 3	0None v	• 0None v	1.
Rotor 4	0None ~	• 0None v	1.
Rotor 5	0None v	• 0None v	1.
Rotor 6	0None ~	0None 🗸	1.
Rotor 7	0None v	• 0None 🗸	1.
Rotor 8	0None ~	• 0None v	1.
Rotor 9	0None v	• 0None v	1.
Rotor 10	0None ~	0None 🗸	1.
Prev	Ne <u>x</u> t	<u>O</u> K	Canc <u>e</u> l



The Select XY Plot Definitions dialog box is used to select which XY Plot Definition entities will be written to the input file as OUTMGT entries

#### Available for:

- SOL 414,103 (Eigenvalue Analysis)
- SOL 414,111 (Harmonic Response)
- SOL 414,129 (Transient Response)

For convenience, this dialog box contains:

- Common icons used throughout Femap for selection and filtering of "named entities"
- Additional icons to highlight Nodes and Elements referenced by XY Plot Definition entities in the graphics window as well as create, edit, and delete XY Plot Definition entities





The Select Rotational Speeds dialog box is used to select which Rotational Speed entities will be written to the input file as OMEGA, OMEGA1, and/or OMEGA2 entries

Available for:

 SOL 414,110 (Complex Modal Analysis) once a Subcase with Analysis Type set to "2..Rotor Complex Modal" has been created

For convenience, this dialog box contains:

- Common icons used throughout Femap for selection and filtering of "named entities"
- Additional icons to create, edit, and delete Rotational Speed entities





## Simcenter Femap 2306

Analysis and Solver Support – Simcenter Nastran – Rotor Dynamics

The *Boundary Conditions* dialog box has been updated to add Load Sets and other options specific for SOL 414 Analysis Types

- Static Load Sets used to select a load set containing static loads
- Dynamic Load Set used to select a load set containing dynamic excitations
- Unbalance Load Set used to select a load set containing Unbalance Mass and/or Unbalance Moment loads
- Fourier Multi-Harmonics (a,b,c THRU d)

   used to request/remove certain
   harmonics for an analysis (text entry)

Boundary Conditions				X
Primary Sets			- Fourier Multi-Harmonic	s ( a,b,c THRU d )
<u>C</u> onstraints	1NASTRAN SPC 1	$\sim$	Harmonics to Requ	est
Constraint Eguations	0From Constraint Set	$\sim$	Harmonics to Remo	ove
Static Load Set	0None	$\sim$	Glue Sets	
Dynamic Load Set	0None	$\sim$	All Connectors	
Initial Temperature Set	0None	$\sim$	O Connection(s)	0None 🗸 📳
Tempe <u>r</u> ature Load Set	0From Load Set	$\sim$	○ None	
Unbalance Load Set	0None	$\sim$	<u>G</u> lue Property	0None v
Pre <u>v</u>	. Ne <u>x</u> t		<u>O</u> K	Canc <u>el</u>



## Simcenter Femap 2306

Analysis and Solver Support – Simcenter Nastran – Rotor Dynamics

Available Input Summary:

- Options section
  - For all SOL 414 Analysis Types
  - NASTRAN Executive and Solution Options
  - NASTRAN Bulk Data Options
  - NASTRAN Rotor Dynamics Options
  - Rotor Modeling Assembly Selection
  - For all SOL 414 except SOL 414,101
    - NASTRAN Dynamic Analysis



- For all SOL 414 except SOL 414,101 and SOL 414,110
  - Select XY Plot Definition(s)
- For SOL 414,129 Only
  - Strategy Parameters (NLCNTLG) Added Axisymmetric Harmonic Coupling Options specifically for this analysis type



#### Available Input Summary:

- Global Requests and Conditions section
  - For all SOL 414 Analysis Types
    - Boundary Conditions
    - NASTRAN Output Requests
  - For SOL 414,129 Only
    - Strategy Parameters (NLCNTL2)

Boundary Conditions			×	
Primary Sets			Fourier Multi-Harmonics ( a,b,c THRU d )	
<u>C</u> onstraints	1NASTRAN SPC 1	$\sim$	Harmonics to Request	
Constraint Eguations	0From Constraint Set	~	Harmonics to Remove	
<u>S</u> tatic Load Set	0None	$\sim$	Glue Sets	
Dynamic Load Set	0None	$\sim$	All Connectors	
Initial Temperature Set	0None	$\sim$	O Connection(s) 0None	
Tempe <u>r</u> ature Load Set	0From Load Set	$\sim$	○ None	
Unbalance Load Set	0None	~	Glue Property 0None ~	
Pre <u>v</u> .	Ne <u>x</u> t		<u>O</u> K Canc <u>e</u> l	-

Available Input Summary (Subcase):

- For all SOL 414 Analysis Types
- *Analysis Case* see specific SOL 414 analysis types
- Boundary Conditions
- NASTRAN Output Requests
- For SOL 414,101 (Maneuvers)
  - Analysis Case No Analysis Types No additional dialog boxes
- For SOL 414,103 (Eigenvalue Analysis)
  - Analysis Case 3 Analysis Types:
  - "1..Static Loads, Constraints"
  - "2..Rotor Eigenvalues" NASTRAN Modal Analysis
  - "3..Transient Preload" Strategy Parameters (NLCNTL2) and Subcase # Time Step

Analysis Case				×	
Case <u>I</u> D Sub <u>t</u> itle	1				
Label					
Manual Con	trol Indard	[	<u>S</u> tart T	ext (Off)	
Start Te	ext Inside Case	[	End To	ext (Off)	
Prev	Ne <u>x</u> t	<u>o</u> k		Cancel	





## Simcenter Femap 2306

Analysis and Solver Support – Simcenter Nastran – Rotor Dynamics

- Available Input Summary (Subcase):
- For SOL 414,110 (Complex Modal Analysis)
  - Analysis Case 2 Analysis Types
    - "1..Static Loads, Constraints"
    - "2..Rotor Complex Modal" NASTRAN Modal Analysis and Select Rotational Speed(s)
- For SOL 414,111 (Harmonic Response)
  - Analysis Case 2 Analysis Types:
    - "1..Static Loads, Constraints"
    - "4..Rotor Harmonic" NASTRAN Dynamic Analysis, NASTRAN Modal Analysis, and Strategy Parameters (NLCNTL2)
- For SOL 414,129 (Transient Response)
  - Analysis Case No Analysis Types Strategy Parameters (NLCNTL2) and Subcase # Time Steps





## Simcenter Femap 2306 Analysis and Solver Support – Simcenter Nastran – SOL 402

Updated name of "Control Options" in Analysis Set Manager tree structure to "Strategy Parameters"

Changed name of dialog box to "Strategy Parameters (NLCNTL2)" and enhanced it to feature tabs (formally):

- Analysis (Analysis Control 2 places)
- *Plasticity/Creep* (Plasticity and Creep Control)
- Time Integration (Time Integration)
- Equilibrium (Equilibrium Iteration and Convergence)
- Time Stepping (Time Stepping and Viscous Material Options)
- Contact (Contact)
- Other (Internal Restart and Diagnostic)

Added Default Tab and Default All buttons







### Simcenter Femap 2306 Analysis and Solver Support – Simcenter Nastran – SOL 402

Additions and Updates for Multi-Step Kinematics (SOL 402) in Analysis Set Manager

- Strategy Parameters (NLCNTL2) Analysis tab
- Added Store Run Option (ISTO) drop-down
- Added Solution Method (IRDY) drop-down
- Added Solution Frequency Option (BALF) drop-down
- Strategy Parameters (NLCNTL2) Equilibrium tab
  - Added Relaxed Force Tol (PRDR) value
  - Added *Relaxed Energy Tol (PRDE)* value
- Strategy Parameters (NLCNTL2) Other tab
  - Added Storage Cycle for Element Stress (IA4) value
  - Added Complex Eigenvalue Frequency Step (IA12) value
- Strategy Parameter (NLCNTLG)
  - Added Check Initial Stiffness (KINI) option can be used in SOL 414 as well

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Simcenter Femap 2306 Analysis and Solver Support – Simcenter Nastran – SOL 402

Updated name of "Control Options" in Analysis Set Manager tree structure to "Strategy Parameters"

Changed name of dialog box to "Strategy Parameters (NLCNTL2)" and enhanced it to feature tabs (formally):

- Analysis (Analysis Control 2 places)
- *Plasticity/Creep* (Plasticity and Creep Control)
- *Time Integration* (Time Integration)
- Equilibrium (Equilibrium Iteration and Convergence)
- *Time Stepping* (Time Stepping and Viscous Material Options)
- Contact (Contact)
- Other (Internal Restart and Diagnostic)

## Added Default Tab and Default All buttons



#### **Simcenter Femap 2306** Analysis and Solver Support – Simcenter Nastran – Response Spectrum Application

Added support for Simcenter Nastran's ability to use the *Relative Method* instead of the *Large Mass Method* for *Base DOF* 

*Relative Method* – writes RSPLOC entry

- RSPLOC Set Constraint set containing nodes where spectrum is to be applied by writing nodes constrained in any DOF to the GIDi fields
- *CSys* writes ID of coordinate system to CID field
- Direction integer corresponding to selected option written to DIR field

When used, ID of RSPLOC is then written to a RSPLOIDi field on the RSAPPLY entry (support added in Femap 2301)

NASTRAN Response Spec	ctrum Application X
Spectrum None Acceleration Velocity Displacement	Spectrum Function ID 11DTI Table, Single Axis Scale Factor 1.
Modal Combination	
Method	5DSUM V
Earthquake Duration	1.
Base DOF O Large Mass Method RSPLOC Set CSys Direction	Relative Method   3RSPLOC DOF   0Global Rectangular   0DOF1
Modal Damping Damping Func	10Modal Damping Function V
Draw	

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### Simcenter Femap 2306 Analysis and Solver Support – Nastran and ABAQUS

Simcenter Nastran and MSC Nastran

- Added support to write/read Femap Layup Titles to/from comments in input files
- Added support to write 0.0 for stiffness values to Spring/Damper properties ("K" values on PBUSH) as this is viable for these solvers

## ABAQUS

- Improvements to exporting load and constraint definitions
- Consistently create \*NSET and \*ELSET from load definitions and constraint definitions
- Create accurate \*NSET and \*ELSET for load definitions and constraint definitions applied on different geometric entities such as points, curves, and/or surfaces
- Appropriately export load Definitions on elements, curves, and points are as \*CLOAD and \*DLOAD
- \*NSET and \*ELSET are referenced in \*BOUNDARY, \*CLOAD, and \*DLOAD to reduce input file size
- Improvements to exporting and importing \*TIE keyword



## Simcenter Femap 2306 Analysis and Solver Support – Analysis Set Manager

Analysis Set Manager

Added *Non-Default Values* branch under *Strategy Parameters* which only displays non-default values specified in the *Strategy Parameters* (*NLCNTL2*) dialog box for Analysis Types:

- "28..Multi-Step Nonlinear Kinematic" (SOL 402)
- "38..Rotor Dynamics Transient Response" (SOL 414,129)

Note: Similar functionality is planned for other Analysis Types in future releases, beginning with "27..Multi-Step Structural" (SOL 401)





# What's new **Simcenter Femap 2306**

- **Teamcenter Integration**
- Geometry
- Preprocessing
- Meshing
- Performance Improvements
- Analysis and Solver Support
- Postprocessing
- Miscellaneous and API



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## **Simcenter Femap 2306** Postprocessing – Support for results from Simcenter Nastran SOL 414 analysis types

Overview of working with results generated by Simcenter Nastran SOL 414 analysis

- VERY IMPORTANT: SOL414 does NOT generate an OP2 results file, thus support was added for attaching to the Simcenter Data File (SCD5) generated by SOL 414
  - SCD5 is based on the HDF5 file format
  - SCD5 is the only output file which can currently be used for post-processing SOL414 results in Femap

	Manage R	esults Files		— 🗆 X
	1	Attached File(s)		Attach Ontions
0	ID 1	Filename s414_110_turbocharger_from_Alain.scd5	File Path D:\Virtual Launch\2023\Rotor_Dynamics_SOL_	File Format  Simcenter Nastran  MSC/MD Nastran
				Comma Separated
				Memory Mapped File
				Unload
File	Info		>	Reload
Sol	ver:			Detach
Ana	alysis Type:			D <u>e</u> tach All
Title	e / Labels:			Locate
				Find File
File	Date:			Save To Model
Mer	mory Mappe	ed:		Done



## **Simcenter Femap 2306** Postprocessing – Support for results from Simcenter Nastran SOL 414 analysis types

The SCD5 results file contains two types of results which are stored in Femap:

- Results for nodes/elements
   which are stored within Output
   Sets as Output Vectors which
   can be plotted in the graphics
   window
- Typically, the results from SOL 414 are displayed a contoured plot, either deformed or animating, based on options specified in Complex Results dialog box



## Simcenter Femap 2306

Postprocessing – Support for results from Simcenter Nastran SOL 414 analysis types

The SCD5 results file contains two types of results which are stored in Femap:

- Results in XY format which are stored as Femap functions which can be viewed in the Charting pane
- Typically, specific functions are selected to generate a "Campbell Diagram", which can be used to determine critical speeds, among other things.
- Lines with 2 points originating at 0,0 are 0P (Green) and 2P (Cyan)
- All other lines are "EigenFrequency vs Rotation Speed" for various modes



![](_page_56_Picture_9.jpeg)

# What's new **Simcenter Femap 2306**

- **Teamcenter Integration**
- Geometry
- Preprocessing
- Meshing
- Performance Improvements
- Analysis and Solver Support
- Postprocessing
- Miscellaneous and API

![](_page_57_Picture_9.jpeg)

![](_page_57_Picture_10.jpeg)

## Simcenter Femap 2306 Miscellaneous – Command Finder Enhancements

## **Command Finder Enhancements**

- Search now includes commands found in Dockable Panes
- If selected command is located within a Pane, the Pane becomes visible
- If selected command is located with a particular "Tool" within a "Toolbox", that tool will be opened and "pulsate" a few times to draw user's attention
- Search now includes "keywords" which are known to be the nomenclature found in other CAE applications
  - For instance, "Equivalence" and "Grids"

		Size	Q	-	8×
Ø	Mesh Sizing (Meshing Toolbox->Mesh Sizin	ng)			
	Default Size (Mesh->Mesh Control->Defau	lt Size)			
	Size At Point (Mesh->Mesh Control->Size	At Point)			
≎۶	Size Along Curve (Mesh->Mesh Control->S	Size Along Curve)			
9	Size On Surface (Mesh->Mesh Control->Siz	ze On Surface)			
8	Size On Solid (Mesh->Mesh Control->Size	On Solid)			
	Interactive (Mesh->Mesh Control->Interactive	tive)			
	Custom Size Along Curve (Mesh->Mesh Co	ontrol->Custom Size Along Cun	ve)		
	Mapped Divisions on Surface (Mesh->Mesh	h Control->Mapped Divisions o	n Sur	face)	

		Equivalence	Q	-	8	×				
‡₽	Coincident Po	Coincident Points (Tools->Check->Coincident Points)								
	Coincident Cu	rves (Tools->Check->Coincider	nt Cu	irves)						
ž	Coincident No	odes (Tools->Check->Coinciden	t No	des)						
#1	Coincident Ele	m (Tools->Check->Coincident	Elem	ı)						
	Coincident Lo	ads (Tools->Check->Coincident	Loa	ds)						
	Coincident Lir	k (Mesh->Connect->Coincider	nt Lir	ık)						
		Equivalence Grids	Q	-	8	×				
[ <b>≭</b> I	Coincident N	odes (Tools->Check->Coincider	nt No	odes)						

SIFM

![](_page_58_Picture_9.jpeg)

## Simcenter Femap 2306 Miscellaneous – Digital Product Experience & Product Excellence Program

## Help Improve the Femap Experience by choosing Program Enrollment options in Help -> Data Privacy

Enhancements to comply with new data privacy laws

Femap collects information about how our customers use the product to help improve product features and user experience

- No proprietary or personally identifiable information is collected
- Participation is completely optional
- Does not affect product performance

![](_page_59_Picture_7.jpeg)

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Added GeometryInterface Object to provide access to all Geometry translators using a single Object

**Rotor Dynamics** 

- Added Objects for new Rotor Dynamics entity types (XY Plot Definition, Bearing Speed Definition, and Rotational Speed Definition)
- Updated Element and Property Objects to support Bearing, Gear, and Fourier Element/Property types
- Updated Analysis Manager and Analysis Case Objects for new options, dialog boxes, etc
- Updated LoadMesh Object for unbalance loads

![](_page_60_Picture_8.jpeg)

Added feFileMessageSelectAll, feFileMessageClear, and feFileMessageSave2 to perform actions in the Messages dockable pane

Added feSurfaceRuled2 to access all available options of the Geometry -> Surface -> Ruled / Between Curves command

Added feMeshSizeSurface2 to access all available options of the Mesh -> Mesh Control -> Size On Surface command

Added Pref\_ViewLogoTransparent to set the "Transparent Logo" option on the "Views" tab of File -> Preferences

![](_page_61_Picture_5.jpeg)

![](_page_61_Picture_6.jpeg)

## **Try Simcenter Femap for free** 30-day free trial

![](_page_62_Picture_1.jpeg)

## Join the Simcenter Femap Community

![](_page_63_Picture_1.jpeg)

**Explore** – Browse our different **blogs** dedicated to each solution, read our articles and hear about the latest news.

![](_page_63_Picture_3.jpeg)

**Share** – Ask questions in our **forum**, get answers, connect with other users, and benefit from their experience.

![](_page_63_Picture_5.jpeg)

**Learn** – Find the information you need in the **knowledge base** and improve your skills.

siemens.com/plm/community/simcenter

![](_page_63_Picture_8.jpeg)

![](_page_63_Picture_9.jpeg)